

Mach3 CNC Controller

File Config Function Cfg's View Wizards Operator PlugIn Control Help

I/O Status

Inputs

Active1

Active2

Active3

Active4

Digitize

LimitOV

Emergency

X++Limit

Y++Limit

X--Limit

Y--Limit

X--Home

Y--Home

Dwell

1

-22.6935

Encoders

1

+0.0000

+0.0000

+0.0000

MPGs

+0.0000

+0.0000

+0.0000

Enable 1

Enable 4

Output1

Output4

PWM Control Ratio

+0.0000

Reset

CS

Engine Configuration... Ports & Pins

Port Setup and Axis Selection Motor Outputs Input Signals Output Signals Encoder/MPG's Spindle Setup Turn Options

Signal	Enabled	Step Pin#	Dir Pin#	Dir LowActive	Step Low Ac...	Step Port	Dir Port
X Axis		8	9			1	1
Y Axis		12	13			1	1
Z Axis		6	7			1	1
A Axis		0	0			0	0
B Axis		0	0			0	0
C Axis		0	0			0	0
Spindle		5	4			1	1

Aceptar Cancelar Aplicar

History Clear

Spindle Pulley

1

Spindle

Coolant

Cycle Start

Single

Feed Hold

Rewind

Edit

QUIT MODE

Diagnosics

IdX +9.5000

IdZ +10.0000

aper +0.0000

ses +0.1000

eed +29.0000

0000 ZERO

0000 ZERO

Inicio

Mach3 CNC Controller

Dibujo - Paint

ES

6:27

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Engine Configuration... Ports & Pins

Port Setup and Axis Selection

Motor Outputs

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Output Signals

Encoder/MPG's

Spindle Setup

Turn Options

Signal	Enabled	Port #	Pin Number	Active Low	Emulated	HotKey
Index		1	15			0
Limit Ovrd		0	0			0
EStop		1	12			0
THC On		0	0			0
THC Up		0	0			0
THC Down		0	0			0
OEM Trig #1		0	0			0
OEM Trig #2		0	0			0
OEM Trig #3		0	0			0
OEM Trig #4		0	0			0
OEM Trig #5		0	0			0

Pins 10-13 and 15 are inputs. Only these 5 pin numbers may be used on this screen

Automated Setup of Inputs

Aceptar

Cancelar

Aplicar

History

Clear

Spindle Pulley

1

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Edit

QUIT MODE

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Mach3 CNC Controller

Dibujo1 - Paint

ES

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Y--Home

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Engine Configuration... Ports & Pins

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Motor Outputs

Input Signals

Output Signals

Encoder/MPG's

Spindle Setup

Turn Options

Signal	Enabled	Port #	Pin Number	Active Low	Emulated	HotKey
OEM Trig #15	<input checked="" type="checkbox"/>	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0
Timing	<input checked="" type="checkbox"/>	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0
Jog X++	<input checked="" type="checkbox"/>	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0
Jog X--	<input checked="" type="checkbox"/>	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0
Jog Y++	<input checked="" type="checkbox"/>	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0
Jog Y--	<input checked="" type="checkbox"/>	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0
Jog Z++	<input checked="" type="checkbox"/>	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0
Jog Z--	<input checked="" type="checkbox"/>	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0
Jog A++	<input checked="" type="checkbox"/>	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0
Jog A--	<input checked="" type="checkbox"/>	0	0	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0

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Automated Setup of Inputs

Aceptar Cancelar Aplicar

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QUIT MODE

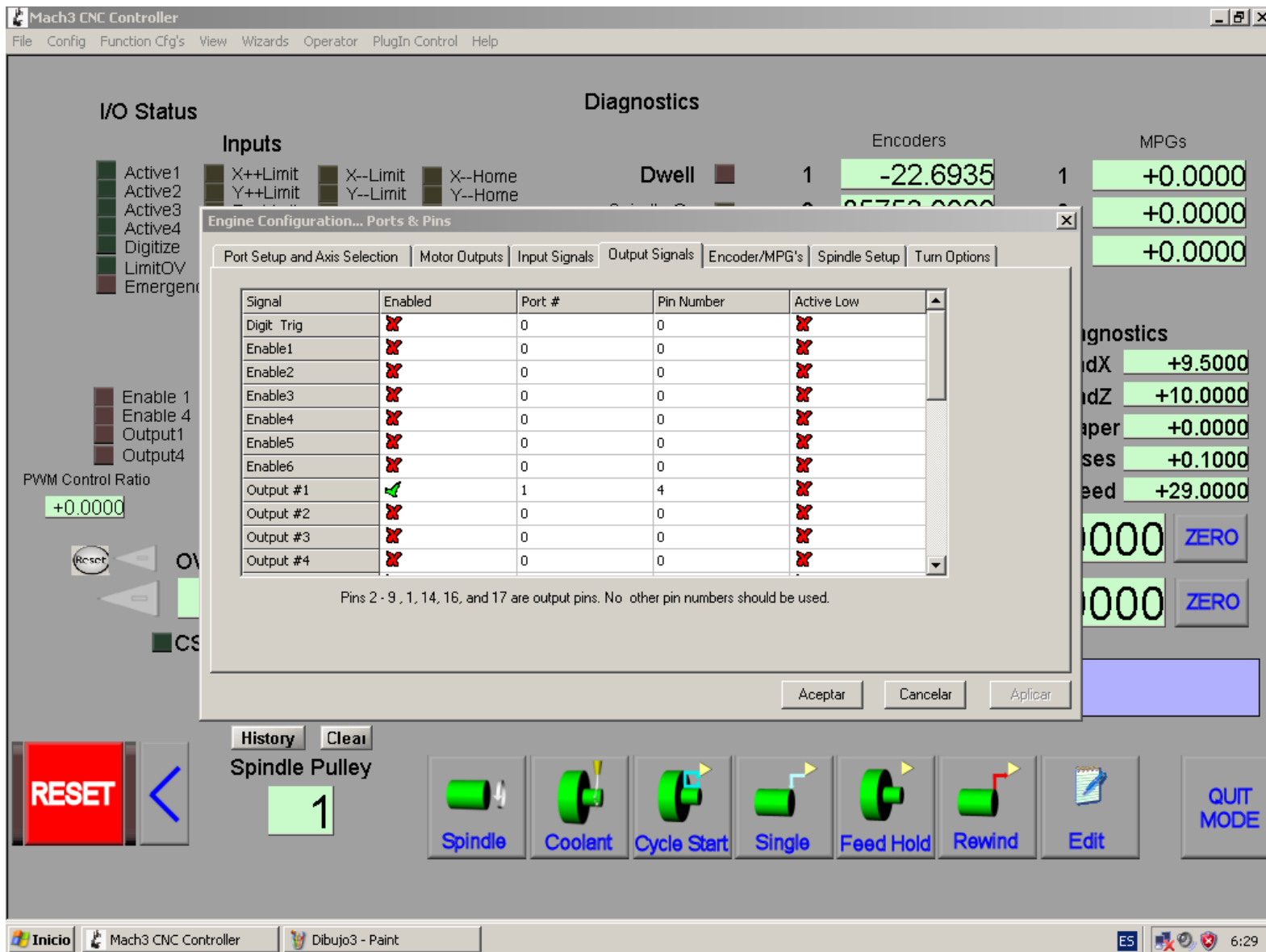
Inicio

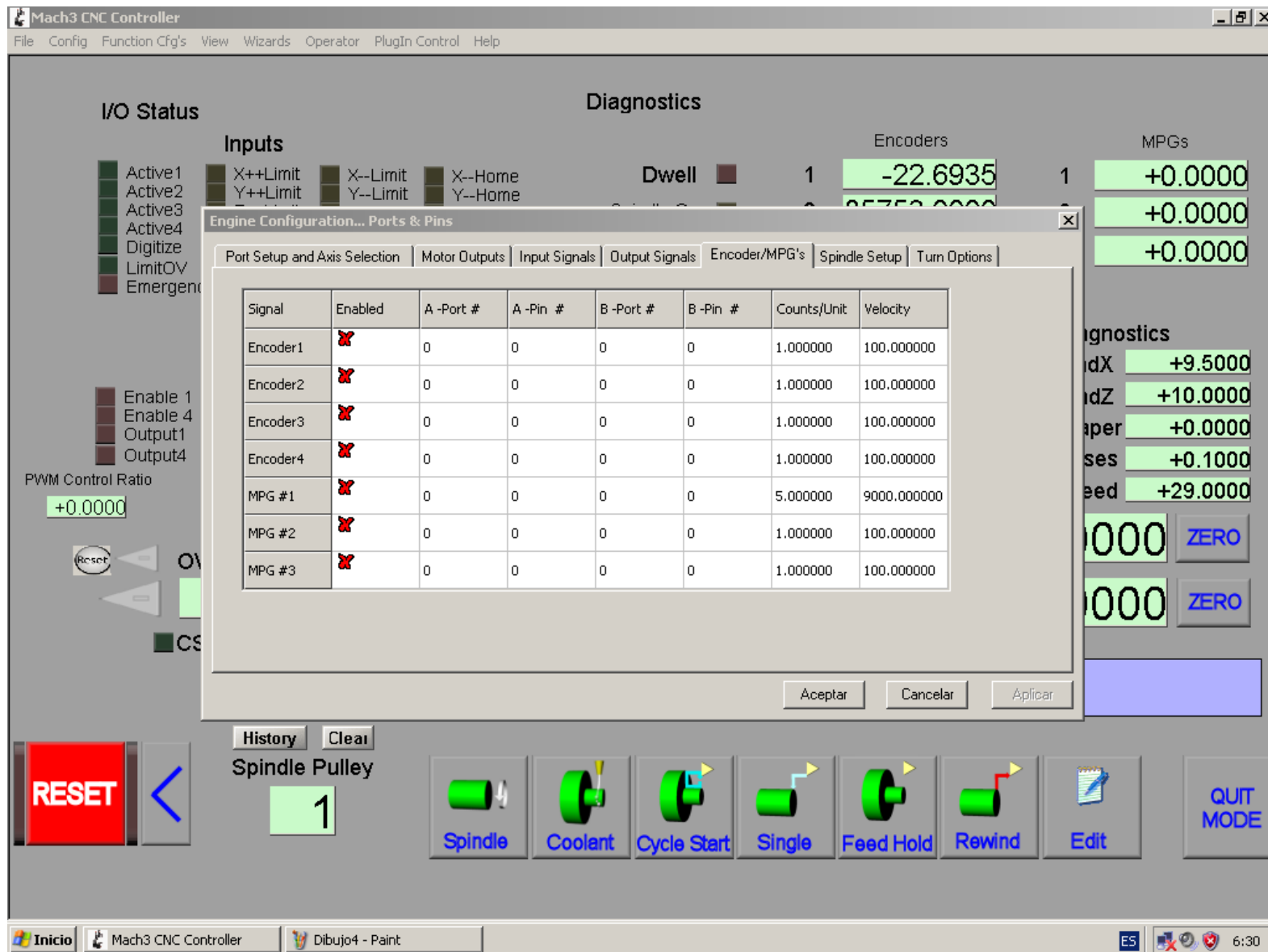
Mach3 CNC Controller

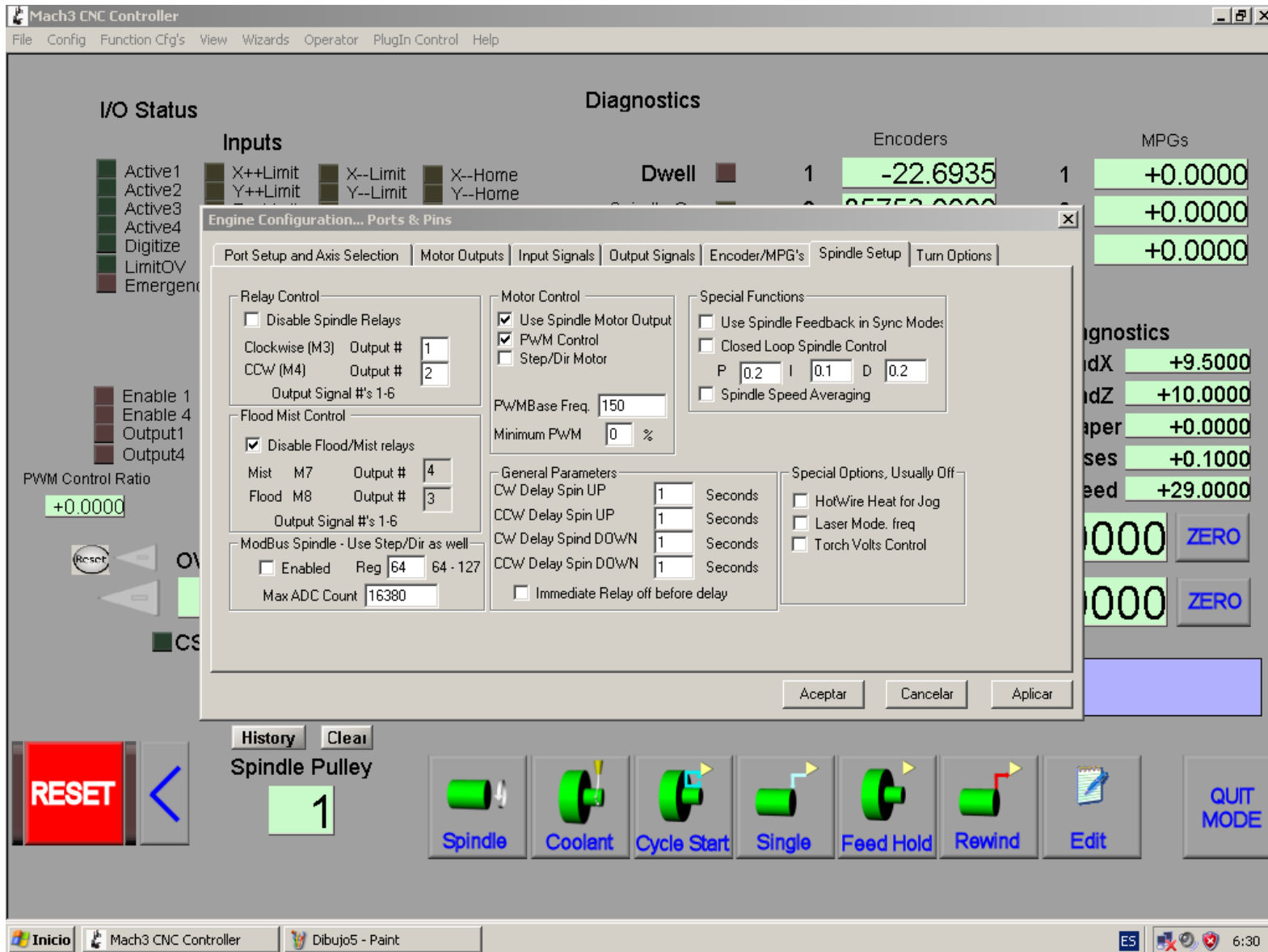
Dibujo2 - Paint

ES

6:28







A two-channel Hall effect encoder is used to sense the rotation of a magnetic disk on a rear protrusion of the motor shaft. The quadrature encoder provides a resolution of 64 counts per revolution of the motor shaft when counting both edges of both channels. To compute the counts per revolution of the gearbox output, multiply the gear ratio by 64. The motor/encoder has six color-coded, 11" (28 cm) leads terminated by a 1×6 female header with a 0.1" pitch, as shown in the main product picture. This header works with standard [0.1" male headers](#) and our male [jumper](#) and [precrimped wires](#). If this header is not convenient for your application, you can pull the crimped wires out of the header or cut the header off. The following table describes the wire functions:

Color	Function
Red	motor power (connects to one motor terminal)
Black	motor power (connects to the other motor terminal)
Green	encoder GND
Blue	encoder Vcc (3.5 – 20 V)
Yellow	encoder A output
White	encoder B output

The Hall sensor requires an input voltage, Vcc, between 3.5 and 20 V and draws a maximum of 10 mA. The A and B outputs are square waves from 0 V to Vcc approximately 90° out of phase. The frequency of the transitions tells you the speed of the motor, and the order of the transitions tells you the direction. The following oscilloscope capture shows the A and B (yellow and



Pololu

37D mm metal gearmotor with 64 CPR encoder (with end cap removed).